# Image Segmentation and convex hull compution

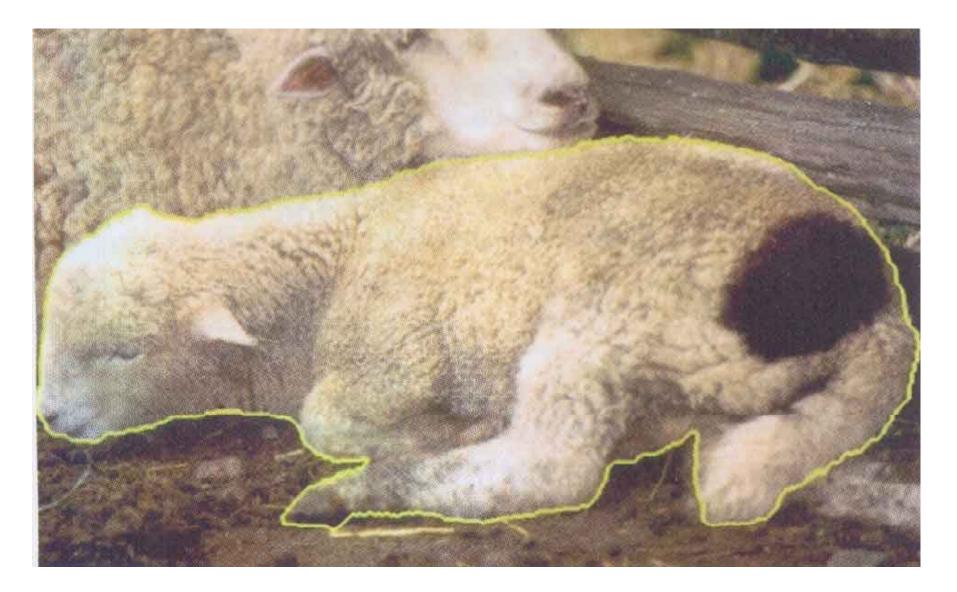




Artificial picture constructed from the segmented images







#### A popular automated system: SNAKES



Input initial boundary curve (rubber-band)

The rubber-band shrinks to capture the region boundary

Question: Can we solve the problem as a simple mathematical problem?

## History

- Goes back to 1994 (15 years ago)
- Tetsuo Asano, Naoki Katoh, and I tried to formulate and solve the image segmentation problem as a geometric optimization problem
- Surprisingly, convex hull plays an important role.





## Image segmentation problem

- $G = n \times n pixel grid (for example, n = 1024)$
- A digital picture is a function **f** (x) on G to represent brightness/color of each pixel x
  - f(x) is real valued (monochromatic picture)
    - In RGB space for color pictures
- **Object image** is a subset S of G to represent an object in the picture.
- Image segmentation: Clip the object image

## Our formulation

- Approximation by two-valued function
  - Picture: function f from G to real values
  - Find the L<sub>2</sub> nearest two-valued function g to f

$$g(p) = a (p \in R)$$
Image  

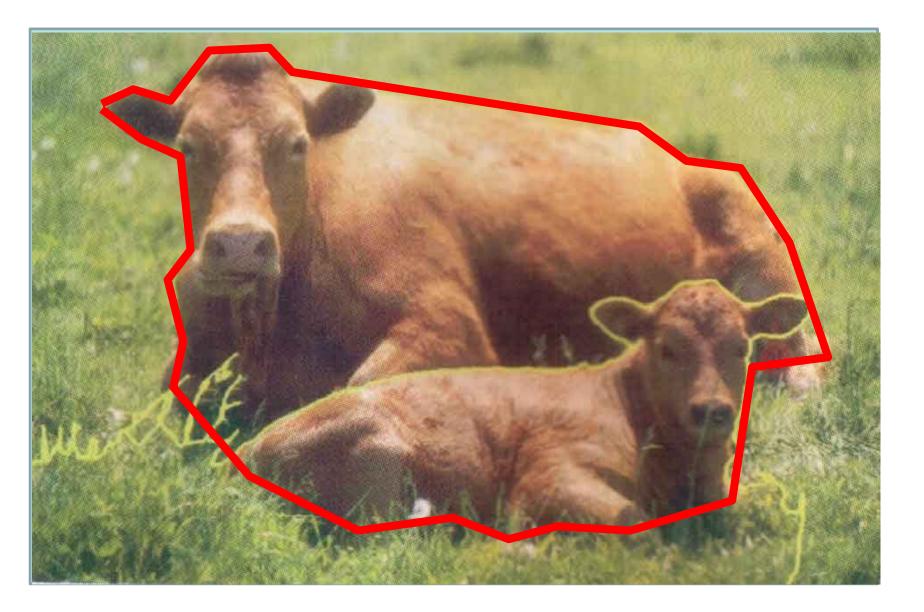
$$g(p) = b (p \notin R)$$
background  
Minimize || f-g ||<sub>2</sub>

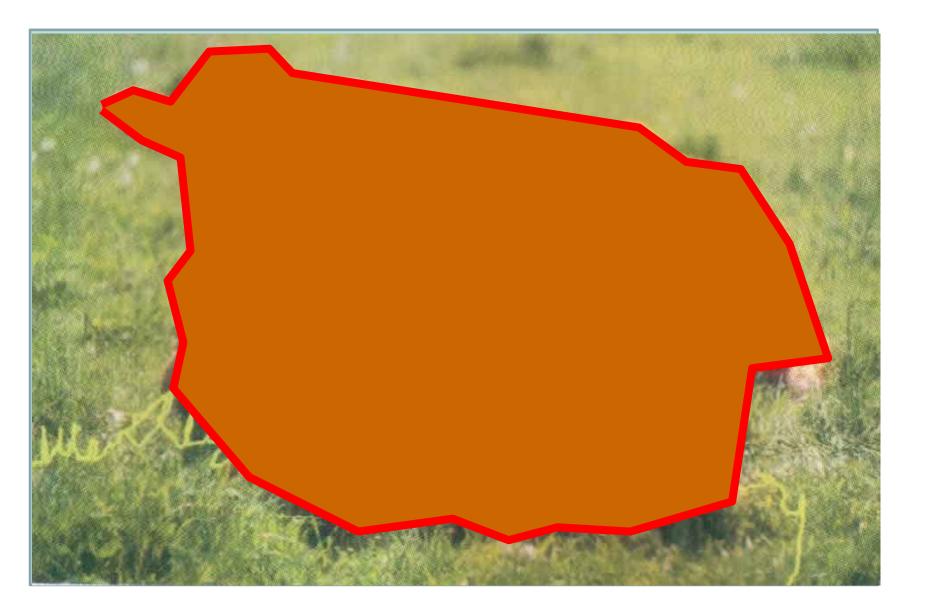
- a and b become average values μ(R) and μ (G-R) of f(p) in R and G-R, respectively.
- That is, minimize the intraclass variance

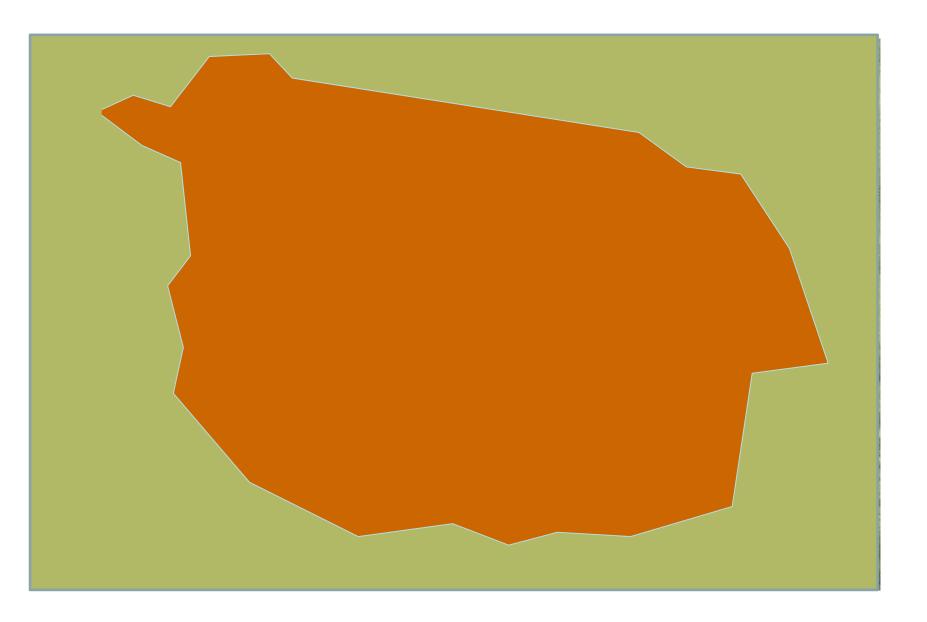
$$Var(R) = \sum_{p \in R} (f(p) - \mu(R))^2 + \sum_{p \in G-R} (f(p) - \mu(G-R))^2$$

Intraclass variance minimization  $Var(R) = \sum_{x \in R} (f(x) - \mu(R))^2 + \sum_{x \in G-R} (f(x) - \mu(G-R))^2$ 

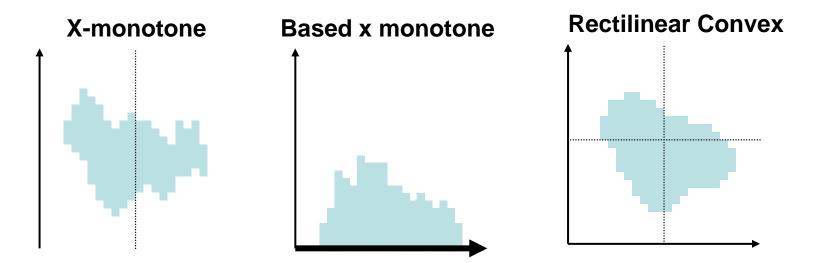
- Easy if R can be arbitrary (disconnected) region.
  Least-square threshold selection (Ohtsu, 1978)
  Collect pixels brighter than a threshold θ
- Reasonable formulation: Give a family **F** of regions of good shapes, and find  $R \in F$  minimizing Var (R)







## **Typical Region Families**



X-monotone: Intersection with any vertical line is a segment. (bounded by two x-monotone chains)

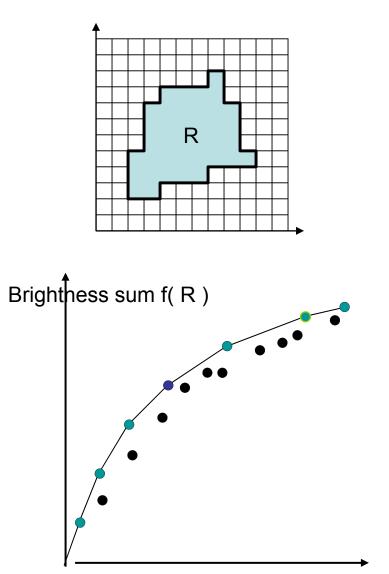
Based (x-)monotone: Region bounded by a monotone chain and a baseline (x-axis)

Rectilinear Convex: X-monotone and Y-monotone region.

## Solution (Asano-Chen-Katoh-T 96)

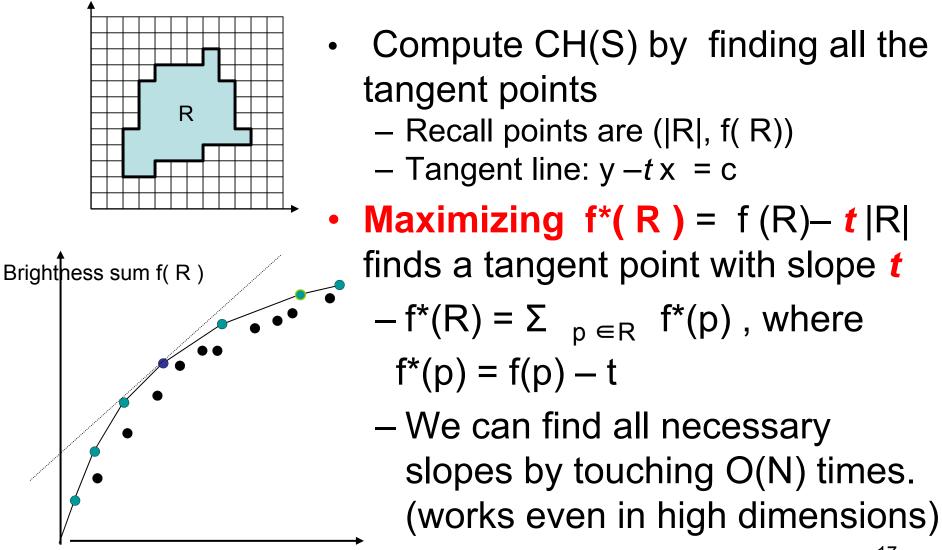
- Idea :
  - If we fix the number k= |R| of pixels in R, Var(R) is minimized if the sum  $f(R) = \sum_{p \in R} f(p)$  is maximized (or minimized).
    - To compute such R is NP-hard even for the base monotone regions
  - Because Var (R) has convexity, we can use convex hull computation to solve it.

### **Convex hull computation**

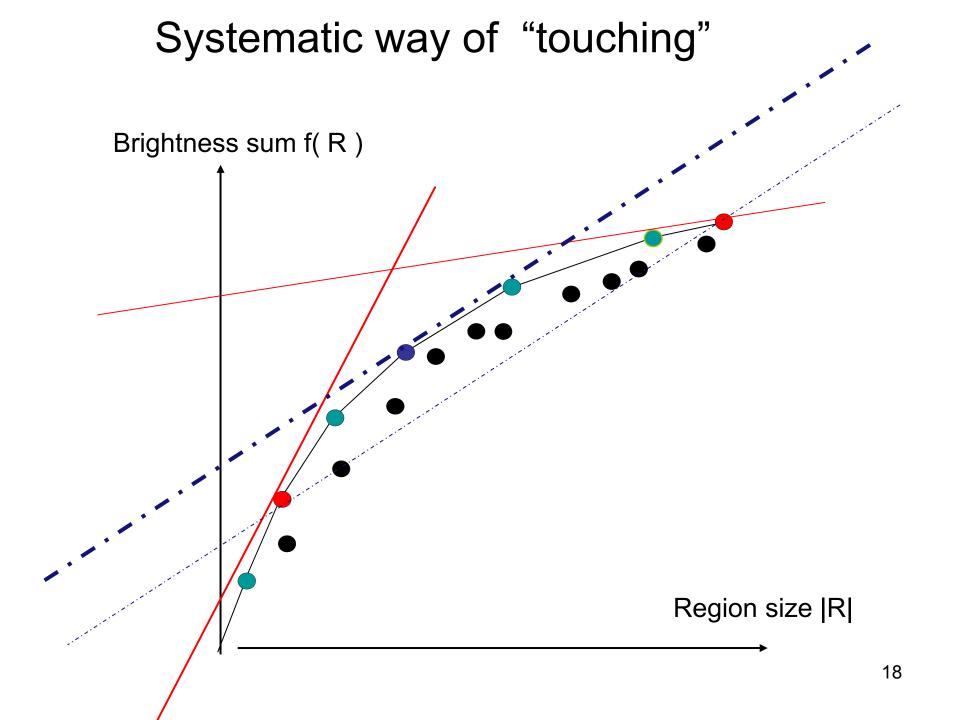


- Consider S = {(|R|, f(R)): R  $\in$  **F**}.
- F has an exponential number of regions in general
- Thus, we cannot compute S
- Fortunately, CH(S) has at most N=n<sup>2</sup> points
  - Output size is small.
- Var(R) is maximized at a point on CH(S) (by its convexity)
- Problem: How can we compute CH(S) without knowing S explicitly

### Convex hull computation by "touching" it



Region size |R|



## The problem we need to solve

Maximum weight region problem: Given a function f\*(p) on G, find the region R in the region family F maximizing f\* (R)

History: Programming Pearls (1984), column 8 (J. Bentley's famous column CACM)

- How to solve it if F is
  - the family of all rectangles
  - the family of all intervals in the onedimensional array

## Maximum weight region

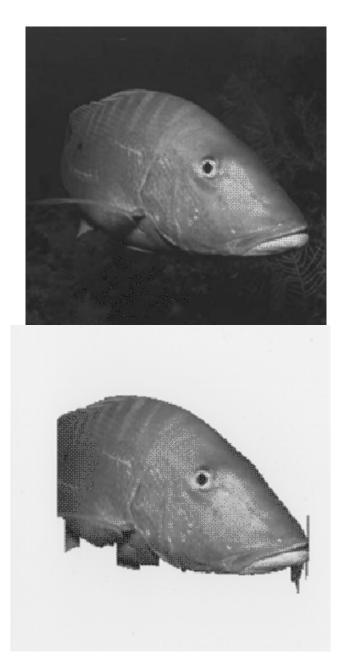
Maximum weight region problem: Given a function f\*(p) on G, find the region R in the region family F maximizing f\* (R)

X-monotone

Easy to solve if **F** is the family of

- Based x-monotone regions
- (Connected) x-monotone regions
- Rectilinear convex regions

NP-hard for the family of all connected regions







# I was lucky to find unexpected applications and extensions

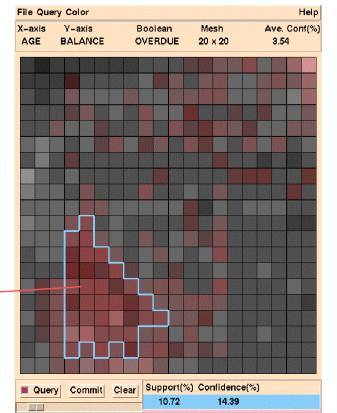
•Data Mining Application: Optimized Numeric Association Rules (SIGMOD 96, VLD96, 98, KDD 97)

#### SONAR

(System for Optimized Numeric Association Rules)

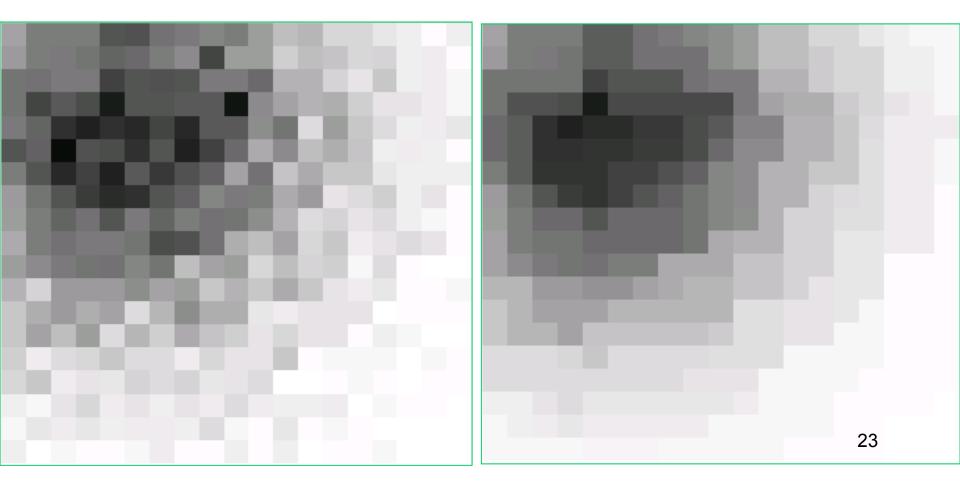
Find a rule to detect unreliable customers using a customer database

(Age, Balance)  $\in \mathbb{R} \iff$  $\Rightarrow$  (CardLoanDelay = yes)



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Pyramid approximation and layered rule (Chun-Sadakane-T 03, Chen-Chun-Katoho-T 04) Instead of two-valued function, we can construct the optimal multilayer function to approximate the input f.



## Remained problems

- The region families are very special
- How to deal with more flexible regions
  - A region consisting of a few basic shapes
  - Convex region, Star-shaped region

